

Robolink Basecamp: Python with CoDrone EDU

Compatibility Chart for use with TI-Nspire CX II

| Unit | Lesson | Compatible for use with TI-Nspire CX II ? | Comment |
|-------------------|--|---|--|
| 0 Getting Started | | | |
| | 0.1 Welcome to Python | Yes | General introduction to Python |
| | 0.2 Python for Robolink | Not applicable | Discusses use of the Python for Robolink online application as the Python coding platform |
| | 0.3 PyCharm | Not applicable | Discusses installation and use of PyCharm as the Python coding platform |
| | Note: The import statement used on TI-Nspire CX II differs slightly from the import statement used by computer based Python applications. If copying and pasting a program created for the computer, be sure to adjust the import statement. When coding on TI-Nspire CX II, the appropriate import statement is applied with the menu selection. >>> Computer apps: from codrone_edu.drone import * >>> TI-Nspire CX II: from codrone_edu import * <i>select the import statement from the menu</i> | | |
| 1 Beginner | | | |
| | 1.1 First Flight | Yes | |
| | 1.2 Flight Movements: Roll & Pitch | Yes | |
| | 1.3 Flight Movements: Throttle and Yaw | Yes | TI-Nspire CX II offers move_up() and move_down() functions in addition to set_throttle() |
| | 1.4 Vars 1: Data Types | Yes | |
| | 1.5 Vars 2: Vars take... | Yes | |
| | 1.6 Conditionals | Yes | |
| | 1.7 For Loops | Yes | |
| | 1.8 While Loops | Yes | |
| 2 Intermediate | | | |
| | 2.1 LEDs and Buzzers | Yes | Brightness is an optional argument for LED methods on TI-Nspire CX II set_drone_LED(R,G,B) - does not require a forth argument for brightness set_controller_LED(R,G,B) - does not require a forth argument for brightness |
| | 2.2 Void Functions | Yes | |
| | 2.3 Return Functions | Yes | |
| | 2.4 Lists | Yes | drone_buzzer() and controller_buzzer() use "C4" with quotes to designate a note instead of Robolink syntax Note.C4 . Selecting a note from the menu on TI-Nspire CX II applies the appropriate note syntax. When making a notes list on TI-Nspire CX II, use ["C4", "D4",...] instead of [Note.C4, Note.D4, ...] TI-Nspire CX II also offers store_list() under the Commands menu for storing lists to the calculator. |
| | 2.5 Random | Yes | Only uses randint() |
| | 2.6 Timers | Yes | Sets start and stop times to test flight times |
| 3 Advanced | | | |
| | 3.1 Sensors Intro | Yes | While TI-Nspire CX II does not include methods for get_angle_x() , get_angle_y() and get_angle_z() , you can use get_heading() on TI-Nspire CX II to obtain an _x() angle. |
| | 3.2 Battery | Yes | OK TI-Nspire CX II monitors battery level and interrupts the program when battery level<50%. |
| | 3.3 Temp & Pressure | Yes | TI-Nspire CX II offers move_up() and move_down() functions in addition to set_throttle() . Also includes a store_list() method. |
| | 3.4 Gyroscope | No | Not available on TI-Nspire CX II |
| | 3.5 Height | Yes | |
| | 3.6 Front Range | Yes | TI-Nspire CX II does not offer avoid_wall() and detect_wall() but these make good programming challenges using get_front_range() |
| | 3.7 Color | Yes | Calibrating color sensor is not available on TI-Nspire CX II, but drone piano will work with some modification. TI-Nspire CX II: var = drone.get_colors() returns a list of 2 elements with the colors detected by the front and the rear color sensors. Color values are: Red, Green, Yellow, Blue, Cyan , Magenta , Black, White, Unknown. Best to use the supplied colored cards (landing pads) that come with CoDrone EDU. |
| 4 Expert | | | |
| | 4.1 User Input | Yes | |
| | 4.2 Kbd Controller | Yes | TI-Nspire CX II has a get_key() method in the TI System module (built in to TI-Nspire CX II menus) which offers an alternative for key presses on the calculator rather than a computer keyboard. Be sure to import the ti_system module into your program. |
| | 4.3 Custom Smart Controller | No | Not available on TI-Nspire CX II |