

Power Engineering
This chapter shows how to handle phasor algebra, complex power, power factor corrections, and unbalanced threephase calculations using the TI-89.

## Topic 19: Phasor Algebra

The sinusoidal, single-frequency voltages and currents of power systems are usually written as phasors - complex numbers in magnitude and phase form. This form is particularly useful in three-phase calculations when phasors must be added or subtracted. For Y-configurations, the line-to-neutral voltages, van, vbn, and ven, (often called the phase voltages) are combined to give the line-to-line voltages, vac, vba, and vcb as shown in Figure 1.


Figure 1. Three-phase line and phase voltages
For a positive phase sequence, the phasor forms of the line to neutral voltages are given as

$$
\begin{aligned}
& \operatorname{van}=110 \\
& \operatorname{vbn}=\operatorname{van} \angle 120^{\circ}=110 \angle 120^{\circ} \\
& \operatorname{vcn}=\operatorname{van} \angle 240^{\circ}=110 \angle 240^{\circ}=110 \angle-120^{\circ}
\end{aligned}
$$

A negative phase sequence gives the opposite signs for the phase angles.

1. Clear the TI-89 by pressing 2nd [F6] 2:NewProb ENTER.
2. The function vphase() uses van and the sign of the phase sequence to calculate the phase voltages (see screen 1). Press APPS 7:Program Editor 3:New, select 2:Function for Type, and enter vphase for Variable. Then type the function lines as shown in screen 1.

See Tips and Generalizations for shortcuts on entering functions.
3. Calculate the phase voltages for van=110 with a positive phase sequence. Return to the Home screen, and use the function vphase() with arguments of 110 and 1 as shown in screen 2.

Two entries are displayed in screen 2 . The first entry shows the returned answer; the second shows the answer scrolled to display the right side.
4. For a negative phase sequence, use arguments of 110 and -1 (screen 3).

If different results are displayed, press MODE and set the modes as shown in the Setup section.
5. Each line-to-line voltage is expressed as the phasor difference of the two adjacent phase voltages, for example, vac=van-vcn. The function phas2lin( ) returns the line-to-line voltages in a list \{vac, vba, vcb\} for van and the sign of the phase sequence.

Enter the function as shown in screen 4 . The function vphase() is used to calculate the phase voltages which then are used to calculate and return the list of line voltages.
6. To calculate the line-to-line voltages for a phase voltage van=110 with a positive phase sequence, use phas2lin() with arguments of 110 and 1 (screen 5). Two entries are displayed again to show the complete answer.


Note: To enter $\angle$, press 2nd [ $\angle]$.

7. Phase voltages are calculated from line-to-line voltages as the difference of the adjacent line voltages, for example, van=(vac-vba)/3. The function lin2phas() returns the phase voltages given the line-to-line voltages and the sign of the phase sequence.

Enter the function shown in screen 6 . The vac line to
 line voltage and phase sequence are used to calculate van which is used to calculate the other two phase voltages.
8. Screen 7 shows the calculation of the phase voltages for vac $=110 \sqrt{3} \angle 30^{\circ}$ and a positive phase sequence.


## Topic 20: Average Power

Instantaneous power is defined as $p(t)=i(t) v(t)$ for real signals where $i(t)$ is the current which flows in the direction of the voltage drop across the element, $v(t) . p(t)$ varies with time as the signal varies. On the other hand, the average power of many signals is constant and often a more useful parameter. It is defined as

$$
\mathrm{P}_{\mathrm{AVG}}=\frac{1}{\mathrm{~T}} \int_{\mathrm{t}=\mathrm{t}_{0}}^{\mathrm{t}_{0}+\mathrm{T}} \mathrm{v}(\mathrm{t}) \mathrm{i}(\mathrm{t}) \mathrm{dt}
$$

where T is the period of the signal.

1. Set the Angle mode to Radian.
2. To calculate the average power dissipated in a $1 \mathrm{k} \Omega$ resistor with a voltage of $v(t)=10 \sin (2 \pi 60 t) V$ across it, first calculate the current as shown in screen 8.

Since $i=v / r$, the current is $i(t)=10 \sin (2 \pi 60 t)$ (bottom of screen 8). The period of this signal is calculated from the relationship $\mathrm{T}=1 / \mathrm{f}=1 / 60 \mathrm{~s}$.
3. Enter the average power, $\mathrm{P}_{\mathrm{AVG}}$, as shown in screen 9 .


The average power is calculated as $1 / 20=50 \mathrm{mw}$.

4. The average power dissipated in a $1 \mu \mathrm{~F}$ capacitor with a voltage of $v(t)=10 \sin (2 \pi 60 t) V$ across it is calculated in a similar way. However, for a capacitor $i(t)=C d v / d t$. The calculator can do the work of calculating the derivative as well as the power. To do this, enter the three expressions as shown in screen 10 .
1 EE ( -9$) 6$ STOD c
$\mathbf{c}$ 2nd $[d] \mathbf{v} \square \mathbf{t} \square \square \mathbf{t} \square$ STOD $\mathbf{i} \square \mathbf{t}$
and

The average power dissipated in a capacitor is always zero!
5. The integral calculation of power is valid when the voltage and current are not so nicely related. For example, consider an unusual device that has a periodic pulse train voltage across it with one cycle defined with the "when" function as shown on the top of screen 11.

$$
\text { CATALOG when( } \mathbf{t} \text { 2nd }[<] \mathbf{0 . 0 1} \square \mathbf{1 0} \square \mathbf{2} \square S T 0 \bullet \mathbf{v} \square \mathbf{t} \square
$$

This device also has a sinusoidal current given by $\mathrm{i}(\mathrm{t})=5 \sin (2 \pi 50 \mathrm{t}+\pi / 4)$, as shown on the bottom of screen 11. These expressions are entered as voltage and current.
6. Note that the two signals must be periodic with the same period $T=0.02$ seconds. To graph the two signals over one period, enter $\mathbf{v}(\mathbf{x})$ and $\mathbf{i}(\mathbf{x})$ in the $\mathrm{Y}=$ Editor (screen 12).
7. Enter the graphing parameters in the Window Editor screen as shown in screen 13.
8. Press [GRAPH] to display the results in the graph in screen 14.

Note: The integral entered before can be copied to the entry line by moving the cursor into the history section with $\Theta$, highlighting the integral, and pressing ENTER.

9. The average power is found by using the same integral over the period of 0.02 seconds. Return to the Home screen, and enter this as shown in screen 15.

$$
\text { 2nd }[\mathrm{s}] \mathbf{v} \square \mathbf{t} \square \mathbf{i} \square \mathbf{t} \square \square \mathbf{t} \square \mathbf{0} \square \mathbf{0 . 0 2 \square \doteqdot \mathbf { 0 } \square} \mathbf{0 . 0 2}
$$

Therefore, the average power dissipated in a device with the square wave voltage and sinusoidal current is 9.00 W .


## Topic 21: Complex Power

For steady-state, sinusoidal signals with $\mathrm{v}(\mathrm{t})=\mathrm{vo} \sin \omega \mathrm{t}$ and $i(t)=i o \sin (\omega t-\theta)$, the average power is calculated with the integral as before where $\mathrm{T}=2 \pi / \omega$.

1. Enter $\mathbf{v}(\mathbf{t})$ and $\mathbf{i}(\mathbf{t})$ as shown in screen 16 .


Note: To enter $\omega$, press $\square$ alpha w.


This form provides the basis for the common expression for average power

$$
\mathrm{P}_{\mathrm{AVG}}=\frac{\mathrm{vo}}{\sqrt{2}} \frac{\text { io }}{\sqrt{2}} \cos \theta
$$

where $\theta$ is the angle by which the current lags the voltage. The terms (vo/ $\sqrt{2}$ ) and (io/ $\sqrt{2}$ ) are known as the root-mean-square (abbreviated as RMS) voltage and current, respectively. RMS quantities are defined as the square root of the mean (or average) of the quantity squared.

$$
\mathrm{xrms}=\sqrt{\frac{\int_{t=0}^{T} x^{2}(t) d t}{T}}
$$

3. Calculate the RMS voltage of $v(t)=v o \sin (\omega \mathrm{t})$ as shown in screen 18.


The result shows that the RMS value of any sinusoidal signal is $\frac{\sqrt{2}}{2}$ times its peak magnitude.


When sinusoidal voltage and current are written in phasor form, vo $\angle 0$ and io $\angle-\theta$, the average power is given as $\mathrm{P}_{\mathrm{AVG}}=\operatorname{Real}(\mathrm{vo} * \operatorname{conj}(\mathrm{io} \angle-\theta)) / 2$.
4. Calculate the average power for $v(t)=v o \sin (\omega t)$ and $i(t)=$ io $\sin (\omega t-\theta)$ using the phasor method.

First enter the voltage phasor as shown in screen 19.

$$
\square \text { vo } \div \text { 2nd }[v] \mathbf{2} \square \text { 2nd }[\angle] \mathbf{0} \square \text { STO } \triangle \text { vphasor }
$$

5. Enter the current phasor (screen 20).
$\square$ io $\div$ 2nd $[\checkmark$ ] $\qquad$ 2nd [ $\angle$ ] $\qquad$ - $[\theta]$ STOD iphasor
6. Calculate the average power (screen 21).

CATALOG real( vphasor $\times$ CATALOG conj( iphasor $\square \square$
The results are identical with the time-domain averaging.

This leads to the generalized concept of complex power. The complex power, S , is defined as $\mathrm{S}=\mathrm{P}+\mathrm{jQ}$ where the real part $P$ is identical to average power and is expressed in watts, the imaginary part $Q$ is known as reactive power expressed in VARs (volt-amperes reactive), and the complex power $S$ has units of VA (volt-amperes). S is calculated by $\mathrm{S}=\mathrm{vo} \angle 0^{*} \operatorname{conj}(\mathrm{io} \angle \theta$ ). The average power is $\mathrm{P}=\operatorname{real}(\mathrm{S})$; the reactive power is $\mathrm{Q}=\mathrm{imag}(\mathrm{S})$.
7. Find the reactive power as shown in screen 22.

CATALOG imag( vphasor $\times$ CATALOG conj( iphasor $\square$
8. Calculation of the complex power for a load of zz1 $=2-\mathrm{j} 3 \Omega$ with a current iphasor1 $=20 \mathrm{~A}$ rms proceeds as follows.
a. First, enter the values of $\mathbf{z z 1}$ and iphasor1 (screen 23).

b. The voltage of the load is vphasor $1=i p h a s o r 1^{*} z z 1$ and the complex power is
$\mathrm{S} 1=\mathrm{vphasor} 1^{*}$ conj(iphasor1) (screen 24).
$\square$ vphasor1 alpha $\times$ CATALOG conj( iphasor1 $\square \square$ STO• s1 2nd [:] s1 CATALOG Rect

The calculation gives s1=800-j1200 VA.
9. Calculation of the complex power associated with a load given by zz $2=3+\mathrm{j} 4 \Omega$ with a voltage of vphasor2=110 Vrms , applied across it proceeds as follows.
a. Press MODE and change the Complex Format mode to RECTANGULAR.
b. First enter zz2 and vphasor2 (screen 25).
c. The rms load current is vphasor2/zz2=iphasor2; the complex power is $\mathrm{S} 2=$ vphasor2*conj(iphasor2).

Enter the complex power as shown in screen 26.
vphasor2 $\times$ CATALOG conj( iphasor2 STO』 s2
The complex power is calculated as $\mathrm{s} 2=1452+\mathrm{j} 1936$
VA. The average power which does work or produces heat in the $3 \Omega$ resistive part of the load is 1452 W . The reactive power which represents the rate of change of stored energy in the $\mathrm{j} 4 \Omega$ reactive part of the load is 1936 VARs.


Note: Two or more commands can be entered on one line using the colon (2nd [:]) to separate them.


Note: setMode('Complex Format", 'Rectangular") was used since the rest of the examples are best displayed in rectangular mode. This can be set with MODE to minimize the typing.


## Topic 22: Power Factor

Complex power $S$ is supplied to a load. The real portion of the power, $P$, is available to do work or produce heat; the imaginary portion of the power, $Q$, is unusable. The fraction of complex power which is available to do work is given by the power factor

$$
\mathrm{pf}=\frac{\text { Real Power }}{\text { Complex Power }}=\frac{\mathrm{P}}{\mathrm{~S}}=\cos \theta
$$

For positive phase angles $\theta$, the power factor is called leading; for negative phase angles, lagging. Resistive loads have a unity power factor, that is, $\mathrm{pf}=1$; reactive loads have a zero power factor. The angle $\theta$ is the same angle as the impedance phase angle. Since $Y=1 / Z$, the admittance phase angle is the negative of the impedance phase angle and can be used to calculate the power factor as well.

The complex power for the load zz1=2-j3 $\Omega$ in Topic 21 is s1=800-j1200 VARs.

1. Find the power factor, pf1 (screen 27).

The power factor of $\mathbf{p f} \mathbf{1}=\frac{2 \cdot \sqrt{13}}{13}$ is lagging since it is a capacitive load, that is, the reactive component is negative.
2. The complex power for the load zz2=3+j4 $\Omega$ in Topic 21 is $\mathrm{s} 2=1452+\mathrm{j} 1936$ VARs.

Screen 28 shows the power factor of $\mathbf{p f} 2=3 / 5$ is leading for the inductive load.


## Topic 23: Power Factor Correction Using Impedances

Reduction of the reactive power improves the power factor which means that more of the power generated by the electric utility can be sold. Therefore, rate incentives are offered for industrial users to improve or "correct" their power factor. Most large users have a leading power due to the inductive nature of motors. A leading power factor can be "corrected," that is, brought closer to unity, by adding capacitors in parallel. The capacitive susceptance, $\mathrm{j} 2 \pi \mathrm{fC}$, cancels part of the inductive susceptance of the load, $-\mathrm{j} \mathrm{B}_{\mathrm{L}}$, and makes the angle $\theta$ smaller and the $\mathrm{pf}=\cos \theta$ closer to unity. See Figure 2.


Figure 2. Admittance triangle
The procedure for calculating the amount of parallel capacitance needed to correct the power factor to unity for the inductive load zz2=3+j4 $\Omega=5 \angle 53.1^{\circ} \Omega$ (Topic 21) follows. This load has pf2 $=\cos \left(53.1^{\circ}\right)=3 / 5=0.6$ (Topic 22).

1. Convert the impedance to admittance, $\mathrm{yy} 2=1 / \mathrm{zz} 2=3 / 25-$ j4/25 = 0.12-j0.16 S (top of screen 29).
2. The added parallel capacitive susceptance must cancel the inductive susceptance so that $\mathrm{j}(0.16)=\mathrm{j} 2 \pi(60) \mathrm{C}$


Note: Calculate the floating-point result by pressing $\square[\approx]$. which gives $\mathrm{C}=424 \mu \mathrm{~F}$ (bottom of screen 29).

Unity power factor is often prohibitively expensive to achieve so the rates are set to offer incentive for partial correction.
Repeat the last example for the load $\mathrm{zz} 2=3+\mathrm{j} 4 \Omega$ but with a final power factor of $\mathrm{pf}=0.9$ leading The load conductance does not change with the addition of the parallel capacitor. To obtain the specified power factor, the added capacitive susceptance must result in a leading $\mathrm{pf}=0.9=\cos \theta$ so that $\tan \theta=\tan \left(\cos ^{-1}(0.9)\right)=-0.484$.

With the addition of the parallel capacitor, the total susceptance of the load is given as btot=imag(yy2) $+2 \pi 60 \mathrm{c}$.

The ratio of imag(s)/real(s) $=(\operatorname{imag}(y y 2)+2 \pi 60 \mathrm{c}) / \mathrm{real}(\mathrm{yy} 2)=\tan \theta=\tan \left(\cos ^{-1}(0.9)\right)$.
Find the desired value of capacitance as shown in screen 30.
CATALOG solve $\square$ CATALOG imag $\operatorname{yy2} \square \square 2$ 2nd $[\pi]$ 60c $\square \square$ CATALOG real( yy2 $\square$ ( --$)$ 2nd [TAN] $\rightarrow\left[\mathrm{COS}^{-1}\right] 0.9 \square \square \square \mathbf{c} \square$
The result is $\mathrm{C}=270 \mu \mathrm{~F}$, somewhat less than that needed for unity power factor and therefore less expensive.


## Topic 24: Power Factor Correction Using Power Triangle

Alternatively, power factor calculations can be made in terms of complex power as well, but these calculations require the voltage or current.

To recalculate the parallel capacitance needed to bring the power factor to 0.9 leading when the complex power is $\mathrm{S} 2=1452+\mathrm{j} 1936 \mathrm{VA}$, recall that $\mathrm{P}=\mathrm{real}(\mathrm{S})$ and $\mathrm{Q}=\mathrm{imag}(\mathrm{S})$ (top of screen 31 ).
Some negative reactive power is introduced by the added parallel capacitance $\mathrm{pf}=0.9=\mathrm{P} / \mathrm{S}=\mathrm{P} /\left(\mathrm{P}+\mathrm{j}\left(\mathrm{Q}-\mathrm{Q}_{\mathrm{CAP}}\right)\right)$.

1. Enter this as shown in screen 31.
```
CATALOG solve( 0.9 }#\mathrm{ p2 - [ CATALOG abs(p2 + 2nd] [i]
\ q2 qcap \, \, qcap \
```

The complete answer is qcap=2639.24 or qcap $=1232.76$
2. Enter the second solution to obtain
$\mathrm{Q}_{\mathrm{CAP}}=1232.8=\left.2 \pi 60 \mathrm{Clv}\right|^{2}=2 \pi 60 \mathrm{C}(\text { |vphasor } 2 \mid)^{2}$.
CATALOG exp list(2nd [ANS], qcap STO cs
and
CATALOG solve(cs 2nd [c] 1 2nd [ $]$ ] 1 2 2nd [ $\pi$ ] 60c $\otimes$ CATALOG abs( vphasor2—— $2 \square$ c $\square$

Screen 32 shows this leads to $\mathbf{c}=270 \mu \mathrm{~F}$, as before.
Note that the second solution cs[2]=2639.2 gives a power factor of 0.9 , but lagging. Since this requires a capacitor twice as large, it is not an economical solution.


Note: $\exp$ list(ans(1),qcap) STO cs is used to convert the results of the first solve into a list which is stored in cs. cs[1] uses the first solution to solve for c .

## Topic 25: $\mathbf{Y}-\Delta$ and $\Delta$ - $\mathbf{Y}$ Transformations

Many circuits are simplified by transforming a circuit from a $Y$ configuration to a $\Delta$ or a $\Delta$ configuration to a Y as shown in Figure 3. The transformation is particularly useful in simplifying circuits for later series-parallel combinations.


Figure 3. $\Delta$ and $Y$ Configurations
The transformations are expressed as

$$
\begin{aligned}
& \mathrm{Z}_{1}=\frac{\mathrm{Z}_{\mathrm{b}} \mathrm{Z}_{\mathrm{c}}}{\mathrm{Z}_{\mathrm{a}}+\mathrm{Z}_{\mathrm{b}}+\mathrm{Z}_{\mathrm{c}}} \quad \mathrm{Z}_{\mathrm{a}}=\frac{\mathrm{Z}_{1} \mathrm{Z}_{2}+\mathrm{Z}_{2} \mathrm{Z}_{3}+\mathrm{Z}_{3} \mathrm{Z}_{1}}{\mathrm{Z}_{1}} \\
& \mathrm{Z}_{2}=\frac{\mathrm{Z}_{\mathrm{c}} \mathrm{Za}^{\mathrm{Z}_{\mathrm{a}}+\mathrm{Z}_{\mathrm{b}}+\mathrm{Z}_{\mathrm{c}}} \quad \mathrm{Z}_{\mathrm{b}}=\frac{\mathrm{Z}_{1} \mathrm{Z}_{2}+\mathrm{Z}_{2} \mathrm{Z}_{3}+\mathrm{Z}_{3} \mathrm{Z}_{1}}{\mathrm{Z}_{2}}}{} \\
& \mathrm{Z}_{3}=\frac{\mathrm{Z}_{\mathrm{a}} \mathrm{Z}_{\mathrm{b}}}{\mathrm{Z}_{\mathrm{a}}+\mathrm{Z}_{\mathrm{c}}} \quad \mathrm{Z}_{\mathrm{c}}=\frac{\mathrm{Z}_{1} \mathrm{Z}_{2}+\mathrm{Z}_{2} \mathrm{Z}_{3}+\mathrm{Z}_{3} \mathrm{Z}_{1}}{\mathrm{Z}_{3}}
\end{aligned}
$$

Since there are multiple inputs and multiple results, functions work well to make these transformations.

1. Press APPS 7:Program Editor 3:New and define the two functions, delta2y() and y2delta(), to implement these equations (screens 33 and 34).
2. Return to the Home screen, and use the delta2y() function to calculate the Y-configuration elements for a delta-configured circuit with $\mathrm{za} \Omega=3+\mathrm{j}, \mathrm{zb}=5+\mathrm{j} 5 \Omega$, and $\mathrm{zc}=2-\mathrm{j} 4 \Omega$ as shown in the middle of screen 35 .
 [i] 4 2nd [1] $\square$


The delta2y() function gives the results $\mathrm{z} 1=2.69-\mathrm{j} 1.54 \Omega$, $\mathrm{z} 2=0.77-\mathrm{j} 1.15 \Omega$, and $\mathrm{z} 3=1.35+\mathrm{j} 1.73 \Omega$ (middle of screen 35 ).
3. The inverse transformation, y2delta(), returns the original impedance values (bottom of screen 35).

## Topic 26: Unbalanced Three-Phase Systems

Solving balanced three-phase Y-systems is quite simple. Since all phases have the same sources and loads, their voltages and currents differ from each other only by $120^{\circ}$. The solution for a single phase is just shifted by $\pm 120^{\circ}$ to get the solutions for the other phases. Although the solutions are more complicated for unbalanced three-phase Y-systems, they are easy with the TI-89's matrix operations.


Figure 4. Unbalanced, three-phase circuit
The three-phase system of Figure 4 has a short-circuit across one phase. The currents can be calculated by using Kirchhoff's voltage law to write three mesh equations for the circuit.

$$
\begin{aligned}
& \mathrm{i} 1(5.6+\mathrm{j} 5.8)-\mathrm{i} 2(0.3+\mathrm{j} 0.4)-\mathrm{i} 3(5.0+\mathrm{j} 5.0)=220-(220 \angle-120) \\
& -\mathrm{i} 1(0.3+\mathrm{j} 0.4)+\mathrm{i} 2(5.6+\mathrm{j} 5.8)-\mathrm{i} 3(5.0+\mathrm{j} 5.0)=(220 \angle 120)+(220 \angle-120) \\
& -\mathrm{i} 1(5+\mathrm{j} 5)-\mathrm{i} 2(5+\mathrm{j} 5)+\mathrm{i} 3(10+\mathrm{j} 10)=0
\end{aligned}
$$

In matrix form, the equations are

$$
\left[\begin{array}{lccc}
5.6+\mathrm{j} 5.8 & -.3-\mathrm{j} .4 & -5 & \mathrm{j} 5 \\
-.3-\mathrm{j} .4 & 5.6+ & \mathrm{j} 5.8 & -5 \\
-55-\mathrm{j} 5 & -5- & \mathrm{j} 5 & 1
\end{array} \mathrm{j} 10\right]\left[\begin{array}{l}
\mathrm{i} 1 \\
\mathrm{i} 2 \\
\mathrm{i} 3
\end{array}\right]=\left[\begin{array}{c}
220-(220 \angle-120) \\
(220 \angle 120)+(220 \angle-120) \\
0
\end{array}\right]
$$

1. Press MODE. Then set Angle mode to DEGREE and Complex Format mode to POLAR.
2. Create a new matrix variable. Press APPS 6:Data/Matrix Editor 3:New. Select 2:Matrix for Type, name the variable unsymnet, and set the row and column dimensions to 3 (screen 36). Press ENTER to display the matrix.

3. Enter the elements from the matrix equation above. Note that you can enter the values in rectangular form. They will automatically be displayed in polar form (screen 37). For j, press 2nd [i].
4. To enter the $3 x 1$ source matrix on the right hand side of the equation, create a new matrix by pressing F1 3:New (screen 38). Select 2:Matrix as the type, name the variable source, and set the row dimension to 3 and column dimension to 1 . Press ENTER.
5. Enter the values from the right hand side of the matrix equation in the same manner (screen 39).
6. Once the matrices are entered, matrix math is all that's needed to find the solution for the current matrix, ii. Return to the Home screen, and enter this as shown in screen 40.

7. The load voltage across the short circuit is zero. The load voltage across the zac is vac $=(\mathrm{i} 1-\mathrm{i} 3)(5+\mathrm{j} 5)$ (screen 41).
8. The load voltage across zbc is vbc=(i2-i3)(5+j5). Enter the expressions as shown in screen 42 . As expected, the two non-zero voltages are the same magnitude, but $180^{\circ}$ out of phase.


Note: Press $\square$ and set the column width to $\mathbf{6}$ to get the display above.


Note: When the first element of a complex number is preceded by a minus sign it must be entered with $(-)$. A minus sign on a following element is entered as $\square$.


## Tips and Generalizations

There are many shortcuts for entering functions. Check under the F2, F33, and F4 menus while in the Program Editor. For example, Local can be entered by pressing F4 3:Local.

The string phase is entered often in the examples in this chapter. To save typing, enter it once and just after pressing e, press and hold $\uparrow$ while pressing © five times (once for each letter in phase).

Finally, release the $\uparrow$ key and press [COPY]. This will save a copy of the highlighted letters so that they can be quickly entered by pressing $\square$ [PASTE].

The TI-89 can easily handle Greek symbols such as $\alpha$ and $\omega$. However, they take four keystrokes each to enter $\square \square$ alpha a and $\square \square$ alpha $\mathbf{w}$ ). If convenience is important, simply use the English equivalents ( $\mathbf{a}, \mathbf{w}$ ) which take only two keystrokes (alpha a or alphal w) or fewer if [a-lock] is already set.
The concept of building a simple function to do repetitive tasks was introduced. Don't underestimate the power of this method. For example, the whole power factor correction example could be written as a function that takes various circuit parameters as an input and returns the capacitor value needed to correct the power factor. Think of the time savings!
Another analysis technique involves the Laplace transform and the s-domain. Chapter 6 shows how the symbolic capabilities of the TI-89 make it the ideal tool for dealing with all of those s's.

