# Welcome to the MATRIX Transforming 2D Space

#### **Student Activity**

7 8 9 10 11 12

# Introduction

The QR codes included here link to three videos related to this activity. The presenter, Grant Sanderson, has produced an entire series on this topic. You don't need to do any calculations whilst watching these three videos, they will however provide an insight to the content in this activity. Scan the QR codes and watch the videos.

TI-Nspire<sup>™</sup>

Investigation

Essence of Linear Algebra

Combinations, span and basis vectors





#### Linear Transformations (matrices)

Student

Teachers Teaching with Technology"



# **Transforming 2 Dimensional Space**

Open the TI-Nspire file: Matrix Trans 1

Page 1.1 contains a brief introduction. Read the instructions then navigate to page 1.2.

The red vector is a transformation of the unit vector:  $\hat{i}$ .

The green vector is a transformation of the unit vector:  $\hat{j}$ 

Point P exists on the Cartesian plane. The coordinates of point P are displayed in the top left corner of the screen.

Point Q is the image of P using the transformation created by the combination of the red and green vectors.

The coordinates for the red and green vectors are displayed in the bottom left corner of the screen. These two vectors can be used to transform the plane.

In the screen shown opposite, the plane has been dilated by a factor of 2 in both the x and y direction.

#### Question: 1.

Suppose point P is moved to (2, 3). Using the same transformation as above, what would be the location of Q?

© Texas Instruments 2022. You may copy, communicate and modify this material for non-commercial educational purposes provided all acknowledgements associated with this material are maintained.

Author: P. Fox



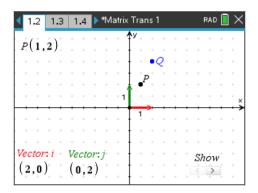
◀ 1.1 1.2 1.3 ▶ Matrix Trans 1

### Transforming 2 Dimensional Space Welcome to the **MATRIX**

RAD

Page 1.2 contains a Graph Application where 2D space is referenced by the Cartesian plane.

The red vector represents the *i*-direction and the green vector represents the *j*-direction. Each vector can be moved to 'morph' the traditional Cartesian plane into a new one. A point P on the original plane is morphed to a point on the new plane as point O.



#### Question: 2.

Suppose point P is at (x, y) and undergoes the same transformation as above, such that point Q is (-6, 8). What would be the coordinates of point P?

#### Question: 3.

Change vector  $\underline{i}$  to a length of 4 units, in the positive *x* direction (only) and vector  $\underline{j}$  to a length of 3 units, in the positive y direction (only). With point P at (1, 2), what are the coordinates of point Q?

#### Question: 4.

Change vector  $\underline{i}$  to a length of 2 units, in the positive *x* direction (only) and return vector  $\underline{j}$  to a unit length (1), in the positive y direction (only). Point P can be placed in each of the locations below.

a) For each location, determine the corresponding coordinates of the transformed point: Q.

P: ( <i>x</i> , <i>y</i> )	(-2, 4)	(-1, 1)	(0, 0)	(1, 1)	(2, 4)
Q: ( <i>x</i> , <i>y</i> )					

b) The location of each point P (above) could be described by a function:  $y = x^2$ .

Study the points generated for Q and determine an appropriate function to describe the location of these transformed points.

At the conclusion of this question, return vectors  $\underline{i}$  and j to 2 units each in the x and y directions respectively.

## The world according to Q.

The show/hide toggle in the bottom right section of the screen allows you to view the transformed plane, "Q's World".

The blue points show how the original  $1 \times 1$  grid has been stretched in both the *x* and *y* direction, each by a factor of 2, just like a scaled drawing.

The coordinates of point Q on the *transformed plane* are: (1, 2), it's position relative to the transformed plane is the same as P on the original plane. Point Q is the image of point P under the transformation of the plane.

In mathematics we are generally interested in the coordinates of Q, relative to the original plane. In reference to the original plane, Q is located at the point: (2, 4).

It is useful to remember that in Q's world, (the transformed plane), it's relative position is unchanged.



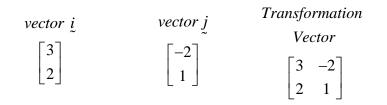
1.1	1.2	1.3	1.3 🕨 *Matrix Trans 1						RAD		<
P(1,	2)	• •	• •	- 1	чу.	• •					•
		•	•	•	•	•2	•			•	•
• • •	•	• •	•		•P	•	•	•			•
					1		•				\$
	•		• •			•	•			•	
Vector		Vecto				• •	•	H	ide '		•
(2,0)	)* *	( <b>0</b> , 2	2) [			• •		<	>		

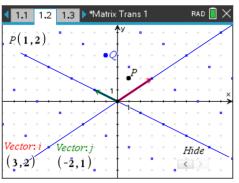


Vectors *i* and *j* can skew the plane. In the diagram shown here, vector *i* has been moved to (3, 2) and vector *j* to (-2, 1). Relative to the skewed plane, Q is still located at: (1, 2).

Relative to the original cartesian plane, Q is located at: (-1, 4)

The transformation can be summarised by a matrix that contains the two vectors:







When the transformed plane is displayed (toggle on), content connected to the *i* and *j* vectors incorporates many calculations slowing the calculator down  $\dots \Theta \oplus \Theta$ .

The calculator will respond quicker if the transformed plane is hidden while vectors are being moved.

#### Question: 5.

The point P can be expressed as a column vector  $\begin{bmatrix} x \\ y \end{bmatrix}$ .

Determine the product of the transformation matrix:  $\begin{bmatrix} 3 & -2 \\ 2 & 1 \end{bmatrix}$  and point P  $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ; comment on the result. a)

- Supposed point P is moved to (2, 3) and undergoes the same transformation, determine the new location of b) point Q (the image of P) under this transformation using matrices and the interactive TI-Nspire diagram.
- and undergoes the same transformation as above such that Q is located at (9, -1). Point P is located at c)

Determine the location of point P.

In the image shown here, the  $\hat{i}$  vector has been moved onto the y axis and dilated by a factor of 3. At the same time the  $\hat{j}$  vector has been moved to the negative x axis and also dilated by a factor of 3. This transformation can be described numerically using the matrix:

$$\begin{bmatrix} 0 & -3 \\ 3 & 0 \end{bmatrix}$$

1.1	1.2	1.3 🕨 *Matrix Trans 1						RA	$] \times$		
P(1,	<u>ئ</u>	• •	•	. 1	У.,	• •			• •		•
$P_{i}(1)$	4).	• •	• •	•		• •	*	*	• •	*	*
		0		1				÷.		÷.	
		~ .			P						
			• •	• 1		• •	+	*		*	• ×
• •	•				1	•	-	•	• •	•	• >
• •			•				+		•		•
Vector	:-i	Vecto		•		• •	*	*	Hid	e '	*
(0,3)	)*	(-3,	<b>0</b> )*				*	)	< )	ľ.	
	- 0	· ·	• •		÷	· •	÷	~	• •	÷	•

© Texas Instruments 2022. You may copy, communicate and modify this material for non-commercial educational purposes provided all acknowledgements associated with this material are maintained

#### Question: 6.

- a) Determine the location of point Q using the transformation matrix (given above).
- b) Compare the distances: |OP| and |OQ|.
- c) Describe the transformation geometrically.

#### Question: 7.

The P (x, y) is transformed such that  $Q\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} -1 & -1 \\ 1 & -1 \end{bmatrix}\begin{bmatrix} x \\ y \end{bmatrix}$  and Q is located at: (-7, -1):

- a) Determine the location of P.
- b) Suppose point P moves along the line: y = x + 1, describe the corresponding location of Q.
- c) Suppose point P moves along the *x* axis, describe the corresponding location of Q.

#### **Question: 8.**

The P (x, y) is transformed such that  $Q\left(\begin{bmatrix} x'\\ y'\end{bmatrix}\right) = \begin{bmatrix} 1 & -1\\ 2 & -2\end{bmatrix}\begin{bmatrix} x\\ y\end{bmatrix}$ :

- a) Move point P and describe the corresponding locations for Q.
- b) Explain what has happened geometrically.
- c) Point Q is located at (2, 4). Determine the location(s) for point P.
- d) Identify another transformation that would have a similar impact.

